

Numerical Analysis

2013 Ph.D. Program Entrance Exam for the Dept. of Math, Nat'l Central Univ.

Problem 1 (System of Linear Equations and Numerical Linear Algebra).

Complete the following.

1. (15%) Let A be a diagonally dominant matrix. State the Gauss-Seidel iterative scheme to obtain the solution to $Ax = b$, and show that the Gauss-Seidel iteration converges for any starting vector.
2. (10%) Let A be an $n \times n$, symmetric and positive definite matrix. Show that the solution to $Ax = b$ is the minimizer of the quadratic form

$$q(x) = \langle x, Ax \rangle - 2\langle x, b \rangle,$$

where $\langle \cdot, \cdot \rangle$ is the inner product on \mathbb{R}^n .

Problem 2 (Approximating Functions).

(15%) Suppose that $f : [0, 1] \rightarrow \mathbb{R}$ is known to be bounded, and continuous at a point $a \in (0, 1)$, and p_n be the Bernstein polynomial of degree n associate to f given by

$$p_n(x) = \sum_{k=0}^n \binom{n}{k} f(k/n) x^k (1-x)^{n-k}.$$

Show that $p_n(a)$ converges to $f(a)$. **Note that f might be continuous at a only.**

Problem 3 (Numerical Differentiation and Integration).

Let $x_i = \frac{i}{n}$. Define two matrices $M, D : \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$ by

$$D = [d_{ij}] \quad \text{with} \quad d_{ij} = \int_0^1 \varphi_i(x) \frac{d\varphi_j}{dx}(x) dx,$$

where $\{\varphi_i\}_{i=1}^{n+1}$ are piecewise linear functions satisfying

1. $\varphi_i(x_{i-1}) = 1$;
2. $\varphi_i(x_k) = 0$ for all $k = 1, 2, \dots, n$ except $k = i - 1$.
3. φ_i is linear in between $[x_{k-1}, x_k]$ for all $k = 1, \dots, n$.

Complete the following.

1. (10%) Use the two-point Gaussian quadrature method; that is,

$$\int_{-1}^1 f(x) dx \approx f\left(-\frac{1}{\sqrt{3}}\right) + f\left(\frac{1}{\sqrt{3}}\right),$$

to find the **exact value** of d_{ij} . Explain why the Gaussian quadrature method can be used to obtain the exact value of the integral.

2. (10%) Explain why D is an approximation of the differential operator in the sense that if $f : [0, 1] \rightarrow \mathbb{R}$ is a function, and vector $F = (f(x_0), f(x_1), \dots, f(x_n))^T$, then $(DF)_i$ is approximately $f'(x_i)$ for all i . Find the order of this approximation.

Problem 4 (Numerical ODE).

(15%) Show that

$$y_{n+1} - y_n = hf\left(x_n + \frac{h}{2}, y_n + \frac{h}{2}f\left(x_n + \frac{h}{2}, y_n + \frac{h}{3}f(x_n, y_n)\right)\right)$$

or equivalently,

$$\begin{aligned} k_1 &= hf(x_n, y_n) \\ k_2 &= hf\left(x_n + \frac{h}{2}, y_n + \frac{k_1}{3}\right) \\ k_3 &= hf\left(x_n + \frac{h}{2}, y_n + \frac{k_2}{2}\right) \\ y_{n+1} &= y_n + k_3 \end{aligned}$$

is a third order method of solving the ODE

$$y' = f(x, y).$$

Problem 5 (Numerical PDE & Newton's method).

In numerical analysis, the **Crank-Nicolson method** is a finite difference method used for numerically solving partial differential equations of the form

$$\frac{\partial u}{\partial t} = F\left(u, x, t, \frac{\partial u}{\partial x}, \frac{\partial^2 u}{\partial x^2}\right),$$

and the Crank-Nicolson method suggests the following second order scheme:

$$\frac{u_k^{n+1} - u_k^n}{\Delta t} = \frac{1}{2} \left[F_k^{n+1}\left(u, x, t, \frac{\partial u}{\partial x}, \frac{\partial^2 u}{\partial x^2}\right) + F_k^n\left(u, x, t, \frac{\partial u}{\partial x}, \frac{\partial^2 u}{\partial x^2}\right) \right],$$

where $u_k^n \equiv u(x_k, n\Delta t)$, and the function F must be discretized spatially with a central difference.

Consider the (nonlinear) Partial Differential Equation

$$\begin{aligned} u_t(x, t) + uu_x - u_{xx}(x, t) &= 0 & \forall x \in [0, 1], t > 0, \\ u(x, 0) &= u_0(x) & \forall x \in [0, 1], \\ u(0, t) = u(1, t) &= 0 & \forall t > 0. \end{aligned}$$

Let $\{0 = x_0 < x_1 < \dots < x_{N-1} < x_N = 1\}$ be a uniform partition of the domain $[0, 1]$, and the time step be $\Delta t \equiv \Delta x^2$.

1. (10%) Let $u^n \equiv (u_1^n, \dots, u_{N-1}^n)^T$. Using the Crank-Nicolson method, one obtains that u^n satisfies the relation

$$G(u^{n+1}) \equiv (I - A)u^{n+1} + f(u^{n+1}) = Au^n - f(u^n), \quad (\star)$$

for some matrix A and nonlinear function f , where I is the identity matrix. Find A and f .

2. (15%) Write down the iterative scheme to solve the nonlinear equation (\star) using Newton's method.