

9: Martingales II

CS 598shp - Randomized Algorithms - Fall 2005

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“The Electric Monk was a labor-saving device, like a dishwasher or a video recorder. Dishwashers washed tedious dishes for you, thus saving you the bother of washing them yourself; video recorders watched tedious television for you, thus saving you the bother of looking at it yourself; Electric Monks believed things for you, thus saving you what was becoming an increasingly onerous task, that of believing all the things the world expected you to believe.” — Dirk Gently’s Holistic Detective Agency, Douglas Adams.

1 Filters and Martingales

Definition 1.1 Given a σ -field (Ω, \mathbb{F}) with $\mathbb{F} = 2^\Omega$, a *filter* (also *filtration*) is a nested sequence $\mathbb{F}_0 \subseteq \mathbb{F}_1 \subseteq \dots \subseteq \mathbb{F}_n$ of subsets of 2^Ω such that

1. $\mathbb{F}_0 = \{\emptyset, \Omega\}$.
2. $\mathbb{F}_n = 2^\Omega$.
3. For $0 \leq i \leq n$, (Ω, \mathbb{F}_i) is a σ -field.

Intuitively, each \mathbb{F}_i define a partition of Ω into *blocks*. This partition is getting more and more refined as we progress with the filter.

Example 1.2 Consider an algorithm A that uses n random bits, and let \mathbb{F}_i be the σ -field generated by the partition of Ω into the blocks B_w , where $w \in \{0, 1\}^i$. Then $\mathbb{F}_0, \mathbb{F}_1, \dots, \mathbb{F}_n$ form a filter.

Definition 1.3 A random variable X is said to be \mathbb{F}_i -*measurable* if for each $x \in \mathbb{R}$, the event $\{X \leq x\}$ is contained in \mathbb{F}_i .

Example 1.4 Let $\mathbb{F}_0, \dots, \mathbb{F}_n$ be the filter defined in Example 1.2. Let X be the parity of the n bits. Clearly, X is a valid event only in \mathbb{F}_n (why?). Namely, it is only measurable in \mathbb{F}_n , but not in \mathbb{F}_i , for $i < n$.

Namely, a random variable X is \mathbb{F}_i -measurable, only if it is a constant on the blocks of \mathbb{F}_i .

Definition 1.5 Let (Ω, \mathbb{F}) be any σ -field, and Y any random variable that takes on distinct values on the elementary elements in \mathbb{F} . Then $\mathbf{E}[X \mid \mathbb{F}] = \mathbf{E}[X \mid Y]$.

2 Martingales

Definition 2.1 A sequence of random variables Y_1, Y_2, \dots , is said to be a *martingale difference* sequence if for all $i \geq 0$,

$$\mathbf{E}[Y_i \mid Y_1, \dots, Y_{i-1}] = 0.$$

Clearly, X_1, \dots , is a martingale sequence **iff** Y_1, Y_2, \dots , is a martingale difference sequence where $Y_i = X_i - X_{i-1}$.

Definition 2.2 A sequence of random variables Y_1, Y_2, \dots , is said to be a *super martingale* sequence if for all $i \geq$,

$$\mathbf{E}[Y_i \mid Y_1, \dots, Y_{i-1}] \leq Y_{i-1},$$

and a *sub martingale* sequence if

$$\mathbf{E}[Y_i \mid Y_1, \dots, Y_{i-1}] \geq Y_{i-1}.$$

Example 2.3 Let U be a urn with b black balls, and w white balls. We repeatedly select a ball and replace it by c balls having the same color. Let X_i be the fraction of black balls after the first i trials. This sequence is a martingale.

Indeed, let $n_i = b + w + i(c - 1)$ be the number of balls in the urn after the i th trial. Clearly,

$$\begin{aligned} \mathbf{E}[X_i \mid X_{i-1}, \dots, X_0] &= X_{i-1} \cdot \frac{(c-1) + X_{i-1}n_{i-1}}{n_i} + (1 - X_{i-1}) \cdot \frac{X_{i-1}n_{i-1}}{n_i} \\ &= \frac{X_{i-1}(c-1) + X_{i-1}n_{i-1}}{n_i} = X_{i-1} \frac{c-1 + n_{i-1}}{n_i} = X_{i-1} \frac{n_i}{n_i} = X_{i-1}. \end{aligned}$$

2.1 Martingales, an alternative definition

Definition 2.4 Let $(\Omega, \mathbb{F}, \mathbf{Pr})$ be a probability space with a filter $\mathbb{F}_0, \mathbb{F}_1, \dots$. Suppose that X_0, X_1, \dots , are random variables such that for all $i \geq 0$, X_i is \mathbb{F}_i -measurable. The sequence X_0, \dots, kX_n is a martingale provided, for all $i \geq 0$,

$$\mathbf{E}[X_{i+1} \mid \mathbb{F}_i] = X_i.$$

Lemma 2.5 Let (Ω, \mathbb{F}) and (Ω, \mathbb{G}) be two σ -fields such that $\mathbb{F} \subseteq \mathbb{G}$. Then, for any random variable X , $\mathbf{E}[\mathbf{E}[X \mid \mathbb{G}] \mid \mathbb{F}] = \mathbf{E}[X \mid \mathbb{F}]$.

$$\begin{aligned}
\text{Proof: } \mathbf{E}\left[\mathbf{E}\left[X \mid \mathbb{G}\right] \mid \mathbb{F}\right] &= \mathbf{E}\left[\mathbf{E}\left[X \mid G = g\right] \mid F = f\right] \\
&= \mathbf{E}\left[\frac{\sum_x x \Pr[X = x \cap G = g]}{\Pr[G = g]} \mid F = f\right] \\
&= \sum_{g \in G} \frac{\frac{\sum_x x \Pr[X = x \cap G = g]}{\Pr[G = g]} \cdot \Pr[G = g \cap F = f]}{\Pr[F = f]} \\
&= \sum_{g \in G, g \subseteq f} \frac{\frac{\sum_x x \Pr[X = x \cap G = g]}{\Pr[G = g]} \cdot \Pr[G = g \cap F = f]}{\Pr[F = f]} \\
&= \sum_{g \in G, g \subseteq f} \frac{\frac{\sum_x x \Pr[X = x \cap G = g]}{\Pr[G = g]} \cdot \Pr[G = g]}{\Pr[F = f]} \\
&= \sum_{g \in G, g \subseteq f} \frac{\sum_x x \Pr[X = x \cap G = g]}{\Pr[F = f]} \\
&= \frac{\sum_x x \left(\sum_{g \in G, g \subseteq f} \Pr[X = x \cap G = g] \right)}{\Pr[F = f]} \\
&= \frac{\sum_x x \Pr[X = x \cap F = f]}{\Pr[F = f]} \\
&= \mathbf{E}\left[X \mid \mathbb{F}\right].
\end{aligned}$$

■

Theorem 2.6 Let $(\Omega, \mathbb{F}, \Pr)$ be a probability space, and let $\mathbb{F}_0, \dots, \mathbb{F}_n$ be a filter with respect to it. Let X be any random variable over this probability space and define $X_i = \mathbf{E}\left[X \mid F_i\right]$ then, the sequence X_0, \dots, X_n is a martingale.

Proof: We need to show that $\mathbf{E}\left[X_{i+1} \mid F_i\right] = X_i$. Namely,

$$\mathbf{E}\left[X_{i+1} \mid F_i\right] = \mathbf{E}\left[\mathbf{E}\left[X \mid F_{i+1}\right] \mid F_i\right] = \mathbf{E}\left[X \mid F_i\right] = X_i,$$

by Lemma 2.5 and by definition of X_i .

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Definition 2.7 Let $f : \mathcal{D}_1 \times \dots \times \mathcal{D}_n \rightarrow \mathbb{R}$ be a real-valued function with arguments from possibly distinct domains. The function f is said to satisfy the *Lipschitz condition* If for any $x_1 \in \mathcal{D}_1, \dots, x_n \in \mathcal{D}_n$, and $i \in \{1, \dots, n\}$ and any $y_i \in \mathcal{D}_i$,

$$|f(x_1, \dots, x_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(x_1, \dots, x_{i-1}, y_i, x_{i+1}, \dots, x_n)| \leq 1.$$

Definition 2.8 Let X_1, \dots, X_n be a sequence of random variables, and a function $f(X_1, \dots, X_n)$ defined over them that such that f satisfies the Lipschitz condition. The *Dobb martingale* sequence Y_0, \dots, Y_m is defined by $Y_0 = \mathbf{E}[f(X_1, \dots, X_n)]$ and $Y_i = \mathbf{E}\left[f(X_1, \dots, X_n) \mid X_1, \dots, X_i\right]$, for $i = 1, \dots, n$. Clearly, Y_0, \dots, Y_n is a martingale, by Theorem 2.6.

Furthermore, $|X_i - X_{i-1}| \leq 1$, for $i = 1, \dots, n$. Thus, we can use Azuma's inequality on such a sequence.

3 Occupancy Revisited

We have m balls thrown independently and uniformly into n bins. Let Z denote the number of bins that remains empty. Let X_i be the bin chosen in the i th trial, and let $Z = F(X_1, \dots, X_m)$. Clearly, we have by Azuma's inequality that $\Pr[|Z - \mathbf{E}[Z]| > \lambda\sqrt{m}] \leq 2e^{-\lambda^2/2}$.

The following is an extension of Azuma's inequality shown in class. We do not provide a proof but it is similar to what we saw.

Theorem 3.1 (Azuma's Inequality - Stronger Form) *Let X_0, X_1, \dots , be a martingale sequence such that for each k ,*

$$|X_k - X_{k-1}| \leq c_k,$$

where c_k may depend on k . Then, for all $t \geq 0$, and any $\lambda > 0$,

$$\Pr[|X_t - X_0| \geq \lambda] \leq 2 \exp\left(-\frac{\lambda^2}{2 \sum_{k=1}^t c_k^2}\right).$$

Theorem 3.2 *Let $r = m/n$, and Z_m be the number of empty bins when m balls are thrown randomly into n bins. Then*

$$\mu = \mathbf{E}[Z_m] = n \left(1 - \frac{1}{n}\right)^m \approx ne^{-r}$$

and for $\lambda > 0$,

$$\Pr[|Z_m - \mu| \geq \lambda] \leq 2 \exp\left(-\frac{\lambda^2(n - 1/2)}{n^2 - \mu^2}\right).$$

Proof: Let $z(Y, t)$ be the expected number of empty bins, if there are Y empty bins in time t . Clearly,

$$z(Y, t) = Y \left(1 - \frac{1}{n}\right)^{m-t}.$$

In particular, $\mu = z(n, 0) = n \left(1 - \frac{1}{n}\right)^m$.

Let \mathbb{F}_t be the σ -field generated by the bins chosen in the first t steps. Let Z_m be the end of empty balls at time m , and let $Z_t = \mathbf{E}[Z_m | \mathbb{F}_t]$. Namely, Z_t is the expected number of empty bins after we know where the first t balls had been placed. The random variables Z_0, Z_1, \dots, Z_m form a martingale. Let Y_t be the number of empty bins after t balls were thrown. We have $Z_{t-1} = z(Y_{t-1}, t-1)$. Consider the ball thrown in the t -step. Clearly:

1. With probability $1 - Y_{t-1}/n$ the ball falls into a non-empty bin. Then $Y_t = Y_{t-1}$, and $Z_t = z(Y_{t-1}, t)$. Thus,

$$\begin{aligned} \Delta_t &= Z_t - Z_{t-1} = z(Y_{t-1}, t) - z(Y_{t-1}, t-1) = Y_{t-1} \left(\left(1 - \frac{1}{n}\right)^{m-t} - \left(1 - \frac{1}{n}\right)^{m-t+1} \right) \\ &= \frac{Y_{t-1}}{n} \left(1 - \frac{1}{n}\right)^{m-t} \leq \left(1 - \frac{1}{n}\right)^{m-t}. \end{aligned}$$

2. Otherwise, with probability Y_{t-1}/n the ball falls into an empty bin, and $Y_t = Y_{t-1} - 1$. Namely, $Z_t = z(Y_t - 1, t)$.

$$\begin{aligned}
\Delta_t &= Z_t - Z_{t-1} = z(Y_{t-1} - 1, t) - z(Y_{t-1}, t-1) \\
&= (Y_{t-1} - 1) \left(1 - \frac{1}{n}\right)^{m-t} - Y_{t-1} \left(1 - \frac{1}{n}\right)^{m-t+1} \\
&= \left(1 - \frac{1}{n}\right)^{m-t} \left(Y_{t-1} - 1 - Y_{t-1} \left(1 - \frac{1}{n}\right)\right) \\
&= \left(1 - \frac{1}{n}\right)^{m-t} \left(-1 + \frac{Y_{t-1}}{n}\right) = -\left(1 - \frac{1}{n}\right)^{m-t} \left(1 - \frac{Y_{t-1}}{n}\right) \\
&\geq -\left(1 - \frac{1}{n}\right)^{m-t}.
\end{aligned}$$

Thus, Z_0, \dots, Z_m is a martingale sequence, where $|Z_t - Z_{t-1}| \leq |\Delta_t| \leq c_t$, where $c_t = \left(1 - \frac{1}{n}\right)^{m-t}$. We have

$$\sum_{t=1}^n c_t^2 = \frac{1 - (1 - 1/n)^{2m}}{1 - (1 - 1/n)^2} = \frac{n^2(1 - (1 - 1/n)^{2m})}{2n - 1} = \frac{n^2 - \mu^2}{2n - 1}.$$

Now, deploying Azuma's inequality, yield the result. ■