



Martingales in finite probability space

Lecturer: Dr. Hong-Gwa Yeh

Department of Mathematics
National Central University

hgyeh@math.ncu.edu.tw

Finite Probability Space

Ω = the set of all possible outcomes of a random experiment (Ω is called a **sample space**, and $\omega \in \Omega$ is called a **sample point**) **note**: we only consider $|\Omega| < \infty$.

σ -algebra: $\mathcal{F} \subseteq 2^\Omega$ is called a σ -algebra if

① $\Omega \in \mathcal{F}$ ② $A \in \mathcal{F} \Rightarrow A^c \in \mathcal{F}$ ③ $A_1, A_2, \dots \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$

EX: Toss a coin 3 times. $\Omega = \{HHH, HHT, HTH, HTT, THH, THT, TTH, TTT\}$

Let $\mathcal{F}_0 = \{\emptyset, \Omega\}$,

$\mathcal{F}_1 = \{\emptyset, \Omega, A_H, A_T\}$, where $A_H = \{HHH, HHT, HTH, HTT\}$

EX (continued) After the random experiment, you are **not told** the outcome, **but you are told**, for every set in \mathcal{F}_1 whether or not the outcome is in that set. For example, you would be told that the outcome is **not in ϕ** , and **is in Ω** . Moreover, you might be told that outcome is **not in A_H** , but is **in A_T** . In effect you have been told that the first toss was a T. We interpret the σ -algebra \mathcal{F}_1 as a record of the "information of the first toss"

$(\Omega, \mathcal{F}, \mathcal{P})$

Probability measure: Let \mathcal{F} be a σ -algebra on Ω .

$\mathcal{P}: \mathcal{F} \rightarrow [0, 1]$ is called a probability measure on (Ω, \mathcal{F})

- ① $\mathcal{P}(\Omega) = 1$ ② If A_1, A_2, \dots is a sequence of disjoint sets in \mathcal{F}
then $\mathcal{P}(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \mathcal{P}(A_i)$

probability space: $(\Omega, \mathcal{F}, \mathcal{P})$ is called a probability space.

a σ -algebra
on Ω

a probability measure
on (Ω, \mathcal{F})

Remark: Here we only consider the case that $|\Omega| < \infty$.

$\alpha(D)$

called block (or atom)

decomposition of Ω : i.e. a collection $\mathcal{D} = \{D_1, D_2, \dots, D_n\}$ of sets in Ω (assume $|\Omega| < \infty$)
s.t. ① $D_i \neq \emptyset \forall i$ ② $D_1 + D_2 + \dots + D_n = \Omega$

Fact: let $\mathcal{F} = \{S : S \text{ is a union of sets in } \mathcal{D}\} \cup \{\emptyset\}$.

Then \mathcal{F} is a σ -algebra, and is called the σ -algebra generated by \mathcal{D} , and is denoted by $\alpha(\mathcal{D})$.

Fact: Let \mathcal{B} be a σ -algebra of subsets of a finite space Ω .

Then $\exists!$ decomposition \mathcal{D} of Ω s.t. $\mathcal{B} = \alpha(\mathcal{D})$

Hint: see Shiryaev p13. Let $\mathcal{D} = \{D \in \mathcal{B} : D \neq \emptyset, D \cap B = D \text{ or } \emptyset \text{ for any } B \in \mathcal{B}\}$.

This \mathcal{D} will meet our need.

\mathcal{G} -measurable

Note*: \exists a one-to-one correspondence between σ -algebras and decomposition of a finite space Ω .

- Let $\mathcal{D} = \{D_1, \dots, D_k\}$ be a decomposition of Ω . $|\Omega| < \infty$
Let $\eta = \eta(\omega)$ be a function on Ω .

Def: η is said to be \mathcal{D} -measurable if η has the form

$$\eta(\omega) = \sum_{i=1}^k \eta_i I_{D_i}(\omega) \quad \text{i.e. } \eta \text{ takes constant values on the blocks of } \mathcal{D}.$$

Remark: In above def. we also said that η is \mathcal{G} -measurable where \mathcal{G} is the σ -algebra $\alpha(\mathcal{D})$

Random Variable X , \mathcal{D}_X

Def: For a finite probability space $(\Omega, \mathcal{F}, \mathcal{P})$, we say that X is a random variable on it if X is an \mathcal{F} -measurable real-valued function defined on Ω .

Def: Let X be a rv having the ^{distinct} values x_1, x_2, \dots, x_k with positive probabilities i.e. $X = \sum_{i=1}^k x_i I_{D_i}(\omega)$, where $D_i = \{\omega \in \Omega : X(\omega) = x_i\}$.

We define the decomposition $\mathcal{D}_X \stackrel{\text{def}}{=} \{D_1, D_2, \dots, D_k\}$.

If X_1, X_2, \dots, X_m are rvs then decomposition $\mathcal{D}_{X_1, X_2, \dots, X_m}$ is defined in the same way.

Note: $\alpha(\mathcal{D}_X)$ is the smallest σ -algebra over which X is measurable.

$P(A|D)$

- (Ω, \mathcal{F}, P) is a finite prob. space. $A \in \mathcal{F}$.
- $D = \{D_1, \dots, D_k\}$ is a decomposition of Ω with $\begin{cases} D_i \in \mathcal{F} & \forall i \\ P(D_i) > 0 & \forall i \end{cases}$

Def: Define the $P(A|D): \Omega \rightarrow \mathbb{R}$ as follows

$$P(A|D)(\omega) = \sum_{i=1}^k P(A|D_i) I_{D_i}(\omega)$$

- Facts:
- (1) $A \cap B = \emptyset \Rightarrow P(A \cup B | D) = P(A|D) + P(B|D)$
 - (2) $P(A|\{\Omega\}) = P(A)$ constant rv
 - (3) $E P(A|D) = P(A)$
 - (4) $P(A|D)$ is D -measurable and hence is \mathcal{F} -measurable
i.e. $P(A|D)$ is a rv.

$E(X|\mathcal{D})$

- (Ω, \mathcal{F}, P) a finite prob. space
- $X: \Omega \rightarrow \{x_1, \dots, x_n\}$ a rv
- $\mathcal{D} = \{D_1, \dots, D_k\}$ a decomposition of Ω st. $D_i \in \mathcal{F}$, $P(D_i) > 0$, $\forall i$.

Def: Def the function $E(X|\mathcal{D}): \Omega \rightarrow \mathbb{R}$ as follows

$$E(X|\mathcal{D})(\omega) = \sum_{i=1}^n x_i P(X=x_i | \mathcal{D})(\omega)$$

Fact: (2) $E(X|\mathcal{D})$ is \mathcal{D} -measurable and hence \mathcal{F} -measurable.
i.e. $E(X|\mathcal{D})$ is a rv.

$$(1) E(X|\mathcal{D}) = \sum_{j=1}^k \left(\sum_{i=1}^n x_i P(X=x_i | D_j) \right) I_{D_j}$$

$$= \sum_{j=1}^k E(X|D_j) I_{D_j}$$

the average value of X on the block D_j

$$(3) E(E(X|\mathcal{D})) = EX$$

$\mathcal{P}(A|\mathcal{F}), \mathcal{E}(X|\mathcal{F})$

Remark: If $\mathcal{F} = \alpha(\mathcal{D})$ then

a σ -algebra of a finite space

$\mathcal{P}(A|\mathcal{D})$ is also denoted by $\mathcal{P}(A|\mathcal{F})$,

and $\mathcal{E}(A|\mathcal{D})$ is also denoted by $\mathcal{E}(A|\mathcal{F})$.

Warning: we only use this notation for finite probability space.

Tower Property

Thm If two σ -algebra \mathcal{F}, \mathcal{G} have $\mathcal{F} \subseteq \mathcal{G}$ then

$$\mathcal{E}(\mathcal{E}(X|\mathcal{G})|\mathcal{F}) = \mathcal{E}(X|\mathcal{F})$$

Fact (1) If X is \mathcal{D} -measurable for a decomposition \mathcal{D} of Ω

then $\mathcal{E}(X|\mathcal{D}) = X$ and $\mathcal{E}(XY|\mathcal{D}) = X \mathcal{E}(Y|\mathcal{D})$
"taking out what is known"

(2) If X is independent of decomposition \mathcal{D} (i.e. $\forall D_i \in \mathcal{D}$, X and I_{D_i} are independent) then $\mathcal{E}(X|\mathcal{D}) = \mathcal{E}X$

pf of (2): Say $\mathcal{D} = \{D_1, \dots, D_k\}$. Then

$$\mathcal{E}(X|\mathcal{D}) = \sum_{i=1}^k \mathcal{E}(X|D_i) I_{D_i} = \sum_{i=1}^k \mathcal{E}X I_{D_i} = \mathcal{E}X.$$

$P(A|X_1, X_2, \dots, X_M)$

- (Ω, \mathcal{F}, P) is a finite prob. space. $A \in \mathcal{F}$
- rv $X: \Omega \rightarrow \{x_1, \dots, x_k\}$ with $P(X=x_i) > 0 \forall i$

Def: $P(A|X) \stackrel{\text{def}}{=} P(A|D_X)$

$$P(A|X_1, X_2, \dots, X_m) \stackrel{\text{def}}{=} P(A|D_{X_1, X_2, \dots, X_m})$$

Facts: (1) $P(A|X)(\omega) = \sum_{i=1}^k P(A|X=x_i) I_{\{X=x_i\}}(\omega)$

(2) $P(A|X_1, X_2, \dots, X_m)(\omega)$

$$= \sum_{y_1, \dots, y_m} P(A|X_1=y_1, \dots, X_m=y_m) I_{\{X_1=y_1, \dots, X_m=y_m\}}(\omega)$$

$E(X|Y_1, Y_2, \dots, Y_M)$

Def: In ^a finite probability space, we define rvs

$$E(X|Y) \stackrel{\text{def}}{=} E(X|D_Y)$$

$$E(X|Y_1, Y_2, \dots, Y_m) \stackrel{\text{def}}{=} E(X|D_{Y_1, Y_2, \dots, Y_m})$$

Fact: The rv $E(X|Y)$ is the rv $f(Y)$ such that $f(y) = E(X|Y=y)$

Pf: Let $Y: \Omega \rightarrow \{y_1, \dots, y_k\}$ with $P(Y=y_i) > 0 \forall i$.

$$E(X|Y) = E(X|D_Y) = \sum_{j=1}^k E(X|D_j) I_{D_j}, \text{ where } D_j = \{Y=y_j\}$$

Done!

Remark: We can generalize the above fact to the rv $E(X|Y_1, \dots, Y_m)$

Example for $E(X | Y_1, Y_2, \dots, Y_m)$

Example Consider independent throws of an unbiased 6-side die. For $1 \leq i \leq 6$, let X_i denote the number of times the value i appears in n throws of the die. Then

$$E(X_1 | X_2) = \frac{n - X_2}{5}, \quad E(X_1 | X_2, X_3) = \frac{n - X_2 - X_3}{4}.$$

pf: $E(X_1 + X_2 + \dots + X_6 | X_2 = \alpha, X_3 = \beta) = n$

$$\Rightarrow 4 E(X_1 | X_2 = \alpha, X_3 = \beta) = n - \alpha - \beta \Rightarrow E(X_1 | X_2 = \alpha, X_3 = \beta) = \frac{n - \alpha - \beta}{4}.$$

$$\Rightarrow E(X_1 | X_2, X_3) = \frac{n - X_2 - X_3}{4}.$$

QED

A filter in finite prob. spaces

- Given a finite probability space $(\Omega, 2^\Omega, \mathcal{P})$.

Def: A filter is a nested sequence of σ -algebras in Ω

s.t. $\{\emptyset, \Omega\} = \mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n = 2^\Omega$

Remark: In above definition, if we have decompositions $\mathcal{D}_0, \dots, \mathcal{D}_n$

s.t. $\mathcal{D}_0 = \{\Omega\}$, $\alpha(\mathcal{D}_i) = \mathcal{F}_i$, $\forall i$, and $\mathcal{D}_n = \{\{\omega\} : \omega \in \Omega\}$

Then sometimes we write the above filter as

$$\{\Omega\} = \mathcal{D}_0 \preceq \mathcal{D}_1 \preceq \dots \preceq \mathcal{D}_n = \{\{\omega\} : \omega \in \Omega\}$$

Martingale (I)

general setting

Def: Given a finite p.s. $(\Omega, 2^\Omega, \mathcal{P})$ with a filter $\{\emptyset, \Omega\} = \mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n = 2^\Omega$, a sequence of rvs X_0, X_1, \dots, X_n is called a **martingale** w.r.t. the filter $\mathcal{F}_0, \mathcal{F}_1, \dots, \mathcal{F}_n$ if $E(X_{k+1} | \mathcal{F}_k) = X_k$ for each $k=0, 1, 2, \dots, n-1$.

Notation: Sometimes we use $(X_k, \mathcal{F}_k)_{k=0}^n$ to denote the above martingale.

Fact: (1) X_k is \mathcal{F}_k -measurable, $k=0, 1, 2, \dots, n$
(2) $E X_k = E X_0$ for each $k=1, 2, \dots, n$.

Martingale (II) special case

Def: A sequence of rvs X_0, X_1, \dots, X_m is called a martingale if for $0 \leq i \leq m$, $E(X_{i+1} | X_0, X_1, \dots, X_i) = X_i$.

Recall: $E(X_{i+1} | X_0, X_1, \dots, X_i) \stackrel{\text{def}}{=} E(X_{i+1} | \mathcal{D}_{X_0, X_1, \dots, X_i})$

Note: In the above definition, X_0, X_1, \dots, X_m is a martingale w.r.t. the filter $\alpha(\mathcal{D}_{X_0}), \alpha(\mathcal{D}_{X_0, X_1}), \alpha(\mathcal{D}_{X_0, X_1, X_2}), \dots, \alpha(\mathcal{D}_{X_0, X_1, \dots, X_m})$ in the general setting.

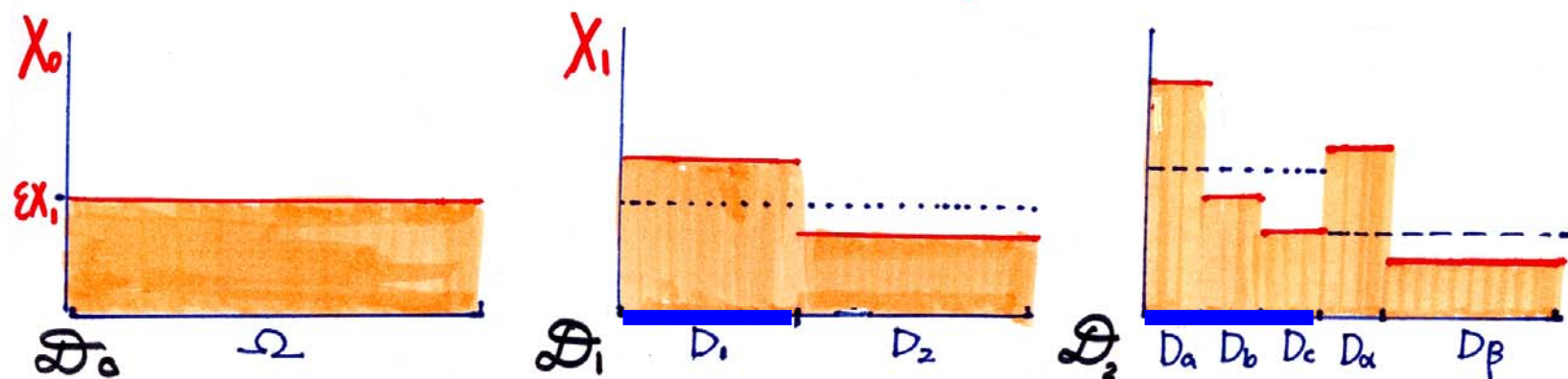
Recall

Suppose $\mathfrak{F}_k = \alpha(\{ D_{k_1}, D_{k_2}, \dots, D_{k_t} \})$.

Then $E(X_{k+1} | \mathfrak{F}_k) = X_k$ implies

$$X_k = \sum_{i=1}^t E(X_{k+1} | D_{k_i}) I_{D_{k_i}}$$

An illustration of a martingale



- We assume that $\alpha(\mathcal{D}_0) = \mathcal{F}_0$, $\alpha(\mathcal{D}_1) = \mathcal{F}_1$, $\alpha(\mathcal{D}_2) = \mathcal{F}_2$.
- The values of X_i are indicated by the *red lines*.

$$X_0 = E X_1 I_{\Omega}$$

Note $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \mathcal{F}_2$.

$$X_1 = E(X_2 | D_1) I_{D_1} + E(X_2 | D_2) I_{D_2}$$

$$X_2 = E(X_3 | D_a) I_{D_a} + E(X_3 | D_b) I_{D_b} + E(X_3 | D_c) I_{D_c} \\ + E(X_3 | D_{\alpha}) I_{D_{\alpha}} + E(X_3 | D_{\beta}) I_{D_{\beta}}$$

Doob Martingales

- Let $(\Omega, 2^\Omega, \mathcal{P})$ be a finite p.s. with a filter $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{F}_n$

Thm Let X be a rv on $(\Omega, 2^\Omega, \mathcal{P})$. Define $X_i = \mathcal{E}(X | \mathcal{F}_i)$ for $i = 0, 1, 2, \dots, n$. Then $(X_i, \mathcal{F}_i)_{i=0}^n$ is a martingale.

pf: For $k = 0, 1, 2, \dots, n-1$, $\mathcal{E}(X_{k+1} | \mathcal{F}_k) = \mathcal{E}(\mathcal{E}(X | \mathcal{F}_{k+1}) | \mathcal{F}_k) = \mathcal{E}(X | \mathcal{F}_k)$ by Tower Thm.

EX: Toss a fair coin three times. Let $X_i = 1$ if i th toss is head, $X_i = 0$ otherwise, $i = 1, 2, 3$. Let $f(X_1, X_2, X_3) = \sum_{i=1}^3 X_i$.

The Doob process. $Y_0 = \mathcal{E}(f(\underline{X}) | \mathcal{F}_0) = \mathcal{E}f(\underline{X}) = \frac{3}{2}$, where $\underline{X} = (X_1, X_2, X_3)$

$$Y_1 = \mathcal{E}(f(\underline{X}) | \mathcal{D}_{X_1}) = \mathcal{E}(\sum_{i=1}^3 X_i | X_1) = X_1 + 1$$

$$Y_2 = \mathcal{E}(f(\underline{X}) | \mathcal{D}_{X_1, X_2}) = \mathcal{E}(f(\underline{X}) | X_1, X_2) = X_1 + X_2 + \frac{1}{2}$$

$$Y_3 = \mathcal{E}(f(\underline{X}) | \mathcal{D}_{X_1, X_2, X_3}) = X_1 + X_2 + X_3$$

$$\{\Omega\} = \mathcal{D}_0 \leq \mathcal{D}_{X_1} \leq \mathcal{D}_{X_1, X_2} \leq \mathcal{D}_{X_1, X_2, X_3} = 2^\Omega, \text{ where}$$

$$\begin{cases} \mathcal{D}_1 = \{ \{X_1=1\}, \{X_1=0\} \} \\ \mathcal{D}_2 = \{ \{X_1=1, X_2=0\}, \{X_1=1, X_2=1\}, \\ \{X_1=0, X_2=1\}, \{X_1=0, X_2=0\} \} \end{cases}$$

Edge Exposure Martingale

- Consider random graph space $\mathcal{G}_{n,p}$. Label the $\binom{n}{2} \stackrel{\text{def}}{=} m$ possible edges with the sequence $1, 2, 3, \dots, m$.

Define the rvs $I_j(\omega) = \begin{cases} 1 & \text{if edge } j \text{ appears in } \omega \\ 0 & \text{o.w.} \end{cases}$

Consider any real-valued function F over $\mathcal{G}_{n,p}$, e.g. the clique number.

The **edge exposure martingale** is defined to be the sequence

of rvs $X_0, X_1, X_2, \dots, X_m$ s.t.

$$X_0 = \mathbb{E}(F)$$

$$X_1 = \mathbb{E}(F | I_1)$$

$$\vdots$$

$$X_{m-1} = \mathbb{E}(F | I_1, I_2, \dots, I_{m-1})$$

$$X_m = F(\mathcal{G}_{n,p})$$

Note: X_0, X_1, \dots, X_m is a Doob martingale.

Vertex Exposure Martingale

- In the same setting as in the edge exposure martingale.

Let $I_{xy}(\omega) = \begin{cases} 1 & \text{if edge } xy \text{ appears in } \omega \\ 0 & \text{o.w.} \end{cases}$

The vertex exposure martingale is defined to be the sequence

of rvs Y_1, Y_2, \dots, Y_n s.t.

$$Y_1 = \mathcal{E}(F)$$

$$Y_2 = \mathcal{E}(F \mid I_{xy}, \{x,y\} \in \left[\begin{smallmatrix} [2] \\ 2 \end{smallmatrix} \right])$$

$$Y_3 = \mathcal{E}(F \mid I_{xy}, \{x,y\} \in \left[\begin{smallmatrix} [3] \\ 2 \end{smallmatrix} \right])$$

\vdots

$$Y_{n-1} = \mathcal{E}(F \mid I_{xy}, \{x,y\} \in \left[\begin{smallmatrix} [n-1] \\ 2 \end{smallmatrix} \right])$$

$$Y_n = F(G_{n,p})$$

Note Y_1, Y_2, \dots, Y_n is

a Doob Martingale.

By ordering the edge appropriately the vertex exposure martingale is a subsequence of the edge exposure martingale.

References

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