

Mathematical Approaches to 2-D Image Processing: A Preliminary Exploration



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July 24, 2022

TWSIAM 2022: Image and Signal Processing

Image processing and computational mathematics

- Tony F. Chan: *Image processing and computational mathematics*, Davis Centre, University of Waterloo, October 7th, 2015.

https://www.youtube.com/watch?v=zZN_L8ntO9I

Image processing has emerged not only as an application domain where computational mathematics provides ideas and solutions but also in spurring new research directions,

“new Computational Fluid Dynamics!”

- We briefly introduce two different mathematical approaches to 2-D image processing:
 - (1) *Variational method/energy functional minimization*
 - (2) *Sparse representation and dictionary learning*

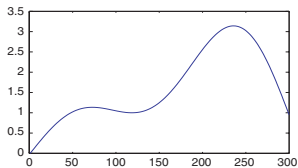
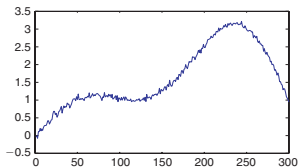
Total variation

Let $u : [a, b] \rightarrow \mathbb{R}$. Let $\mathcal{P}_n = \{x_0 = a, x_1, \dots, x_n = b\}$ be an arbitrary partition of $\bar{\Omega} := [a, b]$ and $\Delta x_i = x_i - x_{i-1}$. The total variation of u is

$$\begin{aligned}\|u\|_{TV(\Omega)} &:= \sup_{\mathcal{P}_n} \sum_{i=1}^n |u(x_i) - u(x_{i-1})| = \sup_{\mathcal{P}_n} \sum_{i=1}^n \left| \frac{u(x_i) - u(x_{i-1})}{\Delta x_i} \right| \Delta x_i \\ &= \int_{\Omega} |u'(x)| dx, \quad \text{if } u \text{ is smooth.}\end{aligned}$$

Denoising is the problem of removing noise from an image:

minimize $\left(\int_{\Omega} |u'(x)| dx + \text{some data fidelity term} \right)$.



1-D example

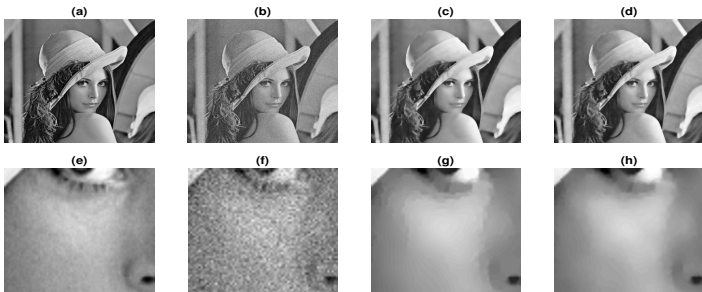
ROF total-variation model vs. adaptive diffusivity model

Let $f : \overline{\Omega} \subset \mathbb{R}^2 \rightarrow \mathbb{R}$ be a given noisy image. Rudin-Osher-Fatemi (1992) proposed the model:

$$\min_{u \in \mathcal{V}} \left(\int_{\Omega} |\nabla u| + \frac{\lambda}{2} (u - f)^2 dx \right), \quad \lambda > 0.$$

Hsieh-Shao-Yang (2018) proposed an adaptive model to alleviate *the staircasing effect*:

$$\min_{u \in \mathcal{V}} \left(\int_{\Omega} \frac{1}{2} \varphi(|\nabla u^*|) |\nabla u|^2 + \frac{\lambda}{2} (u - f)^2 dx \right), \quad \lambda > 0.$$



A variational model for image contrast enhancement

Hsieh-Shao-Yang (2020): for every $f \in \{f_R, f_G, f_B\}$, we solve

$$\min_{u \in \mathcal{V}} \left(\int_{\Omega} |\nabla u - \nabla h_c| dx + \frac{\lambda}{2} \int_{\Omega} (u - g_c)^2 dx \right),$$

where the adaptive functions g_c and h_c are defined as

$$g_c(\mathbf{x}) := \begin{cases} \alpha \bar{f}, & \mathbf{x} \in \Omega_d, \\ f(\mathbf{x}), & \mathbf{x} \in \Omega_b, \end{cases} \quad h_c(\mathbf{x}) := \begin{cases} \beta f(\mathbf{x}), & \mathbf{x} \in \Omega_d, \\ f(\mathbf{x}), & \mathbf{x} \in \Omega_b. \end{cases}$$

Numerical methods: (i) *Euler-Lagrange equation + solving IBVP*; (ii) *direct discretization + split Bregman iterations.*



Numerical results by the split Bregman iterations

Chan-Vese segmentation model: nonconvex minimization

Chan-Vese (1999) modified Mumford-Shah model (1989): two-phase

$$\min_{c_1, c_2, \mathcal{C}} \left(\mu |\mathcal{C}| + \nu |\Omega_{\text{in}}| + \lambda_1 \int_{\Omega_{\text{in}}} (f(x) - c_1)^2 + \lambda_2 \int_{\Omega_{\text{out}}} (f(x) - c_2)^2 \right).$$

In terms of H , δ , and the level set function ϕ , we have

$$\min_{c_1, c_2, \phi} \left(\mu \int_{\Omega} \delta(\phi(x)) |\nabla \phi(x)| + \nu \int_{\Omega} H(\phi(x)) + \lambda_1 \int_{\Omega} (f(x) - c_1)^2 H(\phi(x)) + \lambda_2 \int_{\Omega} (f(x) - c_2)^2 (1 - H(\phi(x))) \right).$$

Numerical method: *an alternating iterative scheme (region averages + solving IBVP of the Euler-Lagrange equation)*



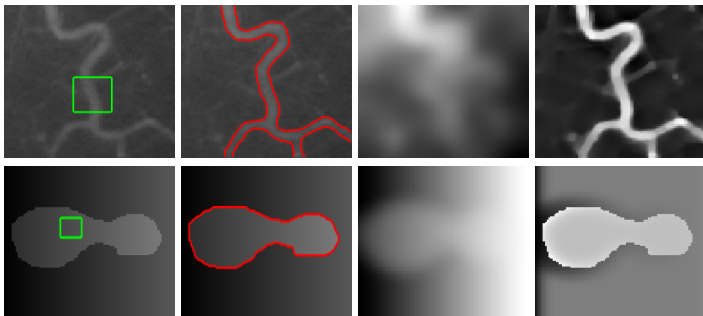
Numerical results by an alternating iterative scheme

Adaptive model for intensity inhomogeneous images

Liao-Yang-You (2022) proposed an entropy-weighted local intensity clustering-based model starting from *the bias field model*: $f = bI + n$:

$$\min_{\mathcal{C}, b, c} \left(\mu |\mathcal{C}| + \int_{\Omega} E_r(\mathbf{y}) \sum_{i=1}^n \int_{\Omega_i} K(\mathbf{y} - \mathbf{x}) (f(\mathbf{x}) - b(\mathbf{y})c_i)^2 dx dy \right).$$

Numerical method: *a new alternating iterative scheme, called iterative convolution-thresholding (ICT) scheme.*



initial contour, segmented result, bias field b, and corrected image f/b

Sparse representation and dictionary learning

SR problem: Given a signal vector $\mathbf{x} \in \mathbb{R}^m$ and a dictionary matrix $\mathbf{D} \in \mathbb{R}^{m \times n}$, $n \gg m$, we seek a coefficient vector $\mathbf{z}^* \in \mathbb{R}^n$ such that

$$\mathbf{z}^* = \arg \min_{\mathbf{z}} \left(\frac{1}{2} \|\mathbf{x} - \mathbf{D}\mathbf{z}\|_2^2 + \lambda \|\mathbf{z}\|_1 \right), \quad \lambda > 0.$$

SDL problem: Let $\{\mathbf{x}_i\}_{i=1}^N \subset \mathbb{R}^m$ be a given dataset of signals. We seek a dictionary matrix $\mathbf{D} = [\mathbf{d}_1, \mathbf{d}_2, \dots, \mathbf{d}_n] \in \mathbb{R}^{m \times n}$ together with the sparse coefficient vectors $\{\mathbf{z}_i\}_{i=1}^N \subset \mathbb{R}^n$ that solve the minimization problem:

$$\min_{\mathbf{D}, \{\mathbf{z}_i\}} \left(\frac{1}{2} \sum_{i=1}^N \|\mathbf{x}_i - \mathbf{D}\mathbf{z}_i\|_2^2 + \lambda \sum_{i=1}^N \|\mathbf{z}_i\|_1 \right)$$

subject to $\|\mathbf{d}_k\|_2 \leq 1, \forall 1 \leq k \leq n, \quad \lambda > 0.$

Numerical method: *alternating direction method of multipliers (ADMM).*

Some applications in image processing

Single image inpainting: *we use the complete patches to train the dictionary, recover the incomplete patches by the sparse representation.*



Other applications: *single image super-resolution, image fusion, ...*

Concluding remarks

Still, there are some other mathematical approaches and important techniques in image processing that need to be further studied, e.g.,

- *Robust PCA (SVD), sparse and low-rank representation, ...*
- *Fast and efficient global registration, convex relaxation techniques, ...*



Image stitching

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Image stitching

Thank you for your attention!